



M - Projective Curvature Tensor Equipped with a ϵ -kenmotsu Manifold

N.V.C. Shukla¹, Mantasha²

¹ Department of Mathematics and Astronomy,, University of Lucknow, Lucknow-226007, Uttar Pradesh, India

¹nvcshukla72 @gmail.com, ²mantasha4554@gmail.com

How to cite this paper:

N.V.C.Shukla, Mantasha, "M - projective curvature tensor equipped with an ϵ -kenmotsu manifold," *Journal of Applied Science and Education (JASE)*, Vol. 05, Iss. 02, S. No. 103, pp 1-8, 2025.

<https://doi.org/10.54060/a2zjournals.jase.103>

Received: 12/02/2025

Accepted: 15/06/2025

Online First: 14/07/2025

Published: 14/07/2025

Copyright © 2025 The Author(s).

This work is licensed under the Creative Commons Attribution International License (CC BY 4.0).

<http://creativecommons.org/licenses/by/4.0/>



Open Access

Abstract

In this paper, we studied the properties of ϵ -Kenmotsu manifolds that possess an M-projective curvature tensor. We have shown that ϵ -Kenmotsu manifolds with an M-projectively flat and irrotational M-projective curvature tensor are locally isometric to the hyperbolic space $H^n(c)$, where $c = -\epsilon^2$. Additionally, we have investigated the condition $R(X, Y)S = 0$ for M-projectively flat ϵ -Kenmotsu manifolds. Then we focused on the analysis of ϵ -Kenmotsu manifolds with a conservative M-projective curvature tensor. Lastly, we have certain geometric results for ϵ -Kenmotsu manifolds that satisfy the relation $M(X, Y)R = 0$.

2020 Mathematics Subject Classification :53C05, 53C20, 53C25, 53D15,53D10.

Keywords

Trans Sasakian manifold, ϵ - Kenmotsu manifold, M-projective curvature tensor, Einstein manifold, η - Einstein manifold , irrotational M-projective curvature tensor and con- servative M-projective curvature tensor

1. Introduction

The basic difference between Riemannian and semi-Riemannian geometry is the existence of a null vector. In a Riemannian manifold (M, g) , the signature of the metric tensor is positive definite, whereas the signature of a semi-Riemannian manifold is indefinite. With the help of indefinite metric Bejancu and Duggal [1] introduced



ϵ -Sasakian manifolds. Then Xufeng and Xiaoli [13] proved that every ϵ -Sasakian manifold must be a real hyperface of some indefinite Kahler manifolds. Since Sasakian manifolds with indefinite metric have applications in Physics [1], we are interested to study various contact manifolds with indefinite metric. Geometry of Kenmotsu manifolds originated from Kenmotsu [10]. In [3] De and Sarkar introduced the notion of ϵ -Kenmotsu manifolds with indefinite metric. On the other hand, in [6] Eisenhart proved that if a Riemannian manifold admits a second order parallel symmetric covariant tensor other than a constant multiple of the metric tensor, then it is reducible. Later on, several authors investigated the Eisenhart problem on various spaces and obtained some interesting results. Recently, Haseeb and De [7] have studied η -Ricci solitons in ϵ -Kenmotsu manifolds. ϵ -Kenmotsu manifolds have also been studied by several authors such as ([2, 8, 9, 13, 15]) and many others. So far, our knowledge about curvature symmetries have not been studied in semi-Riemannian manifolds. In this paper, we are going to study curvature symmetries in ϵ -Kenmotsu manifolds. For curvature symmetries we refer the book of Duggal and Sharma [5]. Sharma [12] characterised a class of contact manifold admitting a vector field keeping the curvature tensor invariant.

Definition 1.1. The M -projective curvature tensor of Riemannian manifold M^n was defined by Pokhariyal and Mishra [18] is of the following form:

$$M(X, Y)Z = R(X, Y)Z - \frac{1}{2(n-1)}[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY], \quad (1)$$

where Q is the Ricci operator defined on

$$S(X, Y) = g(QX, Y).$$

A space form (i.e., a complete simply connected Riemannian manifold of constant curvature) is said to be elliptic, hyperbolic or Euclidean according as the sectional curvature tensor is positive, negative or zero [5]. The authors extensively studied the properties of M -projective curvature tensor on the various manifolds (see, [9, 17, 20, 21, 26, 28]). In this paper, we have studied some special properties of ϵ -Kenmotsu manifold. The purpose of this paper is to study the properties of M -projective curvature tensor in ϵ -Kenmotsu manifolds.

The paper is organized as follows: Section 2 is concerned with preliminaries of ϵ -Kenmotsu manifolds. In section 3, we study the M -projectively flat of ϵ -Kenmotsu manifold. Section 4 deals with the M -projectively flat ϵ -Kenmotsu manifold satisfies the condition $R(X, Y) = 0$. In section 5, we study conservative M -projective curvature tensor of ϵ -Kenmotsu manifold. In section 6, irrotational M -projective curvature tensor of ϵ -Kenmotsu manifold are studied. Section 7 is devoted to studying ϵ -Kenmotsu manifold satisfies the condition $M(X, Y)R = 0$.

2. Preliminaries

An almost contact structure on a n -dimensional differentiable manifold M is a triple (ϕ, ξ, η) , where ϕ is a tensor field of type $(1, 1)$, η is a 1-form and ξ is a vector field such that

$$\phi^2 = -I + \eta\xi, \quad (2)$$

$$\eta(\xi) = 1, \phi\xi = 0, \eta\phi = 0. \quad (3)$$

A differentiable manifold with an almost contact structure is called an almost contact manifold. An almost contact metric manifold is an almost contact manifold endowed with a compatible metric g . An almost contact metric manifold M is said to be an ϵ -almost contact metric manifold if



$$g(\xi, \xi) = \pm 1 = \epsilon, \quad (4)$$

$$\eta(X) = \epsilon g(X, \xi), \text{rank}(\phi) = n - 1, \quad (5)$$

$$g(\phi X, \phi Y) = g(X, Y) - \epsilon \eta(X)\eta(Y), X, Y \in (TM), \quad (6)$$

holds, where ξ is space-like or time-like but it is never a light like vector field. We say that (ϕ, ξ, η, g) is an ϵ -contact metric structure if we have

$$d\eta(X, Y) = g(X, \phi Y). \quad (7)$$

In this case, M is an ϵ -contact metric manifold. An ϵ -contact metric manifold is called an ϵ -Kenmotsu manifold [7] if

$$(\nabla_X \phi)Y = -g(X, \phi Y)\xi - \epsilon \eta(Y)\phi X, \quad (8)$$

holds, where ∇ is the Riemannian connection of g . An ϵ -almost contact metric manifold is a ϵ -Kenmotsu manifold if and only if

$$\nabla_X \xi = \epsilon(X - \eta(X)\xi). \quad (9)$$

The following conditions holds in an ϵ -Kenmotsu manifold [7]:

$$(\nabla_X \eta)(Y) = g(X, Y) - \epsilon \eta(X)\eta(Y), \quad (10)$$

$$\eta(R(X, Y)Z) = \epsilon g(X, Z)Y - g(Y, Z)X, \quad (11)$$

$$R(X, Y)\xi = \eta(X)Y - \eta(Y)X, \quad (12)$$

$$R(\xi, X)Y = \eta(Y)X - \epsilon g(X, Y)\xi, \quad (13)$$

$$S(X, \xi) = -(n - 1)\eta(X), \quad (14)$$

$$Q\xi = -\epsilon(n - 1)\xi, \quad (15)$$

$$S(\phi X, \phi Y) = S(X, Y) + \epsilon(n - 1)\eta(X)\eta(Y). \quad (16)$$

for any vector fields X, Y, Z on M , where R, S and Q denotes the curvature tensor, Ricci tensor and Ricci operator on M .

Definition 2: An ϵ - manifold M is said to be η -Einstein manifold if its Ricci tensor S is of the form

$$S(X, Y) = \lambda_1 g(X, Y) + \lambda_2 \eta(X)\eta(Y), \quad (17)$$

for any vector fields X, Y , where λ_1, λ_2 are smooth functions on M .

If $\lambda_2 = 0$, then η -Einstein manifold becomes Einstein manifold. In view of (2) and (17), we have

$$QX = \lambda_1 X + \lambda_2 \eta(X)\xi \quad (18)$$

Let us consider an ϵ -Kenmotsu manifold. Then putting $X = Y = e_i$ in (17), $i = 1, 2, \dots, n$ and taking summation for $1 \leq i \leq n$, we have

$$r = n\lambda_1 + \epsilon\lambda_2 \quad (19)$$

Now, setting $X = Y = \xi$ in (17) and using (2), (3) and (14), we obtain

$$-(n - 1) = \epsilon\lambda_1 + \lambda_2 \quad (20)$$

From the conditions (19) and (20), gives

$$\lambda_1 = \epsilon - \frac{r}{(1 - n)} \quad (21)$$

$$\lambda_2 = \frac{r}{\epsilon} - \frac{n\epsilon}{\epsilon} + \frac{n\epsilon}{(1 - n)\epsilon} \quad (22)$$



where, r is the scalar curvature.

In view of (8) – (11), it can be easily constructed that in n -dimensional ϵ -kenmotsu manifold M , the M -projective curvature tensor satisfies the following condition from (1.1):

$$\begin{aligned}
 M(X, Y)\xi &= [\eta(X)Y - \eta(Y)X] - \frac{1}{2(n-1)}[-(n-1)\eta(Y)X + (n-1)\eta(X)Y \\
 &\quad + \epsilon\eta(Y)QX - \epsilon\eta(X)QY] \\
 M(\xi, X)Y &= \frac{1}{2}[\eta(Y)X - \epsilon g(X, Y)\xi] - \frac{1}{2(n-1)}[S(X, Y)\xi - \epsilon\eta(Y)QX]
 \end{aligned} \quad (23)$$

3. M-Projectively flat ϵ -kenmotsu manifold

In this section, we study M -Projectively flat ϵ -kenmotsu manifold.

Definition 3.1. The Lorentzian ϵ -kenmotsu manifold M is said to be a M -projectively flat, if we have $M(X, Y)Z = 0$. (24)

for any vector fields X, Y, Z on M .

By taking into account of relation (1) and using definition, we get

$$R(X, Y)Z = \frac{1}{2(n-1)}[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY], \quad (25)$$

Taking $Z = \xi$ in (25) and using relations (3), (12) and (14), we have

$$\epsilon[\eta(X)Y - \eta(Y)X] = \frac{1}{n-1}[\eta(Y)QX - \eta(X)QY], \quad (26)$$

Again putting $Y = \xi$ in (26) and using (2), (3) in (14), we get

$$QX = -(n-1)\epsilon X, \quad (27)$$

which on simplification gives,

$$S(X, Y) = -(n-1)\epsilon g(X, Y), \quad (28)$$

which yields,

$$r = -(n-1)\epsilon, \quad (29)$$

Thus, we get the following theorem.

Theorem If an n -dimensional ϵ -kenmotsu manifold is M -Projectively flat, then it is an Einstein manifold and its Ricci tensor of M has the form

$$S(X, Y) = -(n-1)\epsilon g(X, Y). \quad (30)$$

In consequences of (28), (25) becomes

$$R(X, Y)Z = -\epsilon g(Y, Z)X - g(X, Z)Y. \quad (31)$$

A Space form is said to be hyperbolic if the sectional curvature tensor is negative [5]. Thus, we can state

Theorem 3.1. If an n -dimensional ϵ -kenmotsu manifold is M -Projectively flat, then it is either locally isometric to the hyperbolic space $H(c)$, where $c = -\epsilon$ or M has the constant scalar curvature of the form $-(n-1)\epsilon$.



4. M -Projectively ϵ -kenmotsu manifold satisfying the condition $R(X, Y).S = 0$

In this section, we consider that manifold is an M -Projectively flat ϵ -kenmotsu manifold satisfying the condition $R(X, Y).S = 0$. Thus we have

$$S(R(X, Y)Z, U) + S(Z, R(X, Y)U) = 0. \quad (32)$$

In view of (25) in (32), we have

$$\frac{1}{2(n-1)}[S(QX, U)g(Y, Z) - S(QY, U)g(X, Z) + S(QX, Z)g(Y, U) - S(QY, Z)g(X, U)] = 0. \quad (33)$$

Putting $Y = Z = \xi$ in (33) and using the relation (2), (3) and (14), then we have

$$\frac{1}{2(n-1)}[S(QX, U)g(\xi, \xi) - S(Q\xi, U)g(X, \xi) + S(QX, \xi)g(\xi, U) - g(X, U)S(Q\xi, \xi)] = 0 \quad (34)$$

Again, using (14) in (34), we have

$$\epsilon S(QX, U) - (n-1)^2 \eta(U)\eta(X) + \epsilon \eta(U)S(QX, \xi) - \epsilon(n-1)^2 g(X, U) = 0. \quad (35)$$

Let λ be the eigen value of endomorphism Q corresponding to an eigen-vector X . Then putting $QX = \lambda X$ in (35) and using the relation $g(QX, Y) = S(X, Y)$, then we find that

$$\epsilon \lambda^2 g(X, U) - (n-1)^2 \eta(U)\eta(X) - \epsilon \lambda(n-1)\eta(U)\eta(X) - \epsilon(n-1)^2 g(X, U) = 0 \quad (36)$$

Now, putting $U = \xi$ in (36), we get

$$[\lambda^2 + \epsilon \lambda(n-1) - 2(n-1)^2 \epsilon^2] \eta(X) = 0. \quad (37)$$

In this case, since $\eta(X) \neq 0$, the relation (37) gives that

$$[\lambda^2 + \epsilon(n-1)\lambda - 2(n-1)^2 \epsilon^2] = 0. \quad (38)$$

From the above equation it follows that the endomorphism Q has two different non-zero eigen values, namely, $2(n-1)\epsilon$ and $-3(n-1)\epsilon$. Hence, we state the following theorem

Theorem 4.1. *Let M be an n -dimensional M -Projectively ϵ -kenmotsu manifold satisfying the condition $R(X, Y).S = 0$, then symmetric endomorphism Q of the tangent space corresponding to S has two different non-zero eigen values.*

5. Conservative M -Projective curvature tensor on ϵ -kenmotsu manifold

Definition 5.1. An ϵ -kenmotsu manifold (M, g) is said to be M -Projective conservative if

$$\text{div} M = 0, \quad (39)$$

where div denotes the divergence.

Taking the covariant derivative of (1), we get

$$(\nabla_U M)(X, Y)Z = (\nabla_U R)(X, Y)Z - \frac{1}{2(n-1)}[(\nabla_U S)(Y, Z)X - (\nabla_U S)(X, Z)Y + g(Y, Z)(\nabla_U Q)X - g(X, Z)(\nabla_U Q)Y] \quad (40)$$

Contracting with respect to U in (40), we obtain

$$(\text{div} M)(X, Y)Z = (\text{div} R)(X, Y)Z - \frac{1}{2(n-1)}[(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) + g(Y, Z)\text{div} QX - g(X, Z)\text{div} QY] \quad (41)$$

We know that



$$\text{Div} Q(X) = \frac{1}{2} \nabla_X r. \quad (42)$$

$$(\text{div} M)(X, Y)Z = (\text{div} R)(X, Y)Z - \frac{1}{2(n-1)}[(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) + \frac{1}{2}g(Y, Z)\nabla_X r - \frac{1}{2}g(X, Z)\nabla_Y r] \quad (43)$$

But from [7], we have

$$\text{div} M = (\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z). \quad (44)$$

Again, by virtue of (39) and (44) in (43), it reduces to

$$[(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z)] = \frac{1}{2(2n-3)}[g(Y, Z)\nabla_X r - g(X, Z)\nabla_Y r]. \quad (45)$$

Putting $X = \xi$ in (45), we get

$$(\nabla_\xi S)(Y, Z) - (\nabla_Y S)(\xi, Z) = \frac{1}{2(2n-3)}[g(Y, Z)\nabla_\xi r - g(\xi, Z)\nabla_Y r]. \quad (46)$$

Further, we know that

$$(\nabla_\xi S)(X, Y) = \xi S(X, Y) - S(\nabla_\xi X)Y - S(X, \nabla_\xi Y) \quad (47)$$

$$(L_\xi g)(Y, Z) = L_\xi g(Y, Z) - g(L_\xi Y, Z) - g(Y, L_\xi Z) \quad (48)$$

Now put $X = \xi$ in (48) and using (10)

$$(L_\xi g)(Y, Z) = g(\nabla_Y \xi, Z) + g(Y, \nabla_Z \xi) \quad (49)$$

$$(L_\xi g)(Y, Z) = 2\epsilon[g(Y, Z) - \eta(Y)\eta(Z)] \quad (50)$$

Notice that $g(QX, Y) = S(X, Y)$ and using (50), we get

$$(L_\xi S)(Y, Z) = 2\epsilon[S(Y, Z) + (n-1)\eta(Y)\eta(Z)] \quad (51)$$

Making use of (10) and (51) in (47), we get

$$(\nabla_\xi S)(Y, Z) = 0, \quad (52)$$

which yields

$$\nabla_\xi r = 0. \quad (53)$$

In view of (45) and making use of (3), (10), (16), (52) and (53), we obtain

$$\epsilon S(Y, Z) + (\epsilon - 1)g(Y, Z) = -\frac{1}{2(2n-3)}\eta(Z)\nabla r(Y) \quad (54)$$

Now interchanging Y by ϕY and Z by ϕZ in (54) and using (3), (7) and (10), we get

$$S(Y, Z) = -\frac{1}{\epsilon}(\epsilon - 1)g(Y, Z) + (\epsilon - 1)\eta(Y)\eta(Z) \quad (55)$$

Hence, we state the following:

Theorem 5.1. Let M be an n -dimensional M -Projective curvature tensor on ϵ -kenmotsu manifold is conservative, then M is an η -Einstein manifold and Ricci tensor of M has the form $S(Y, Z) =$

$$-\frac{1}{\epsilon}(n-1)g(Y, Z) + (\epsilon-1)\eta(Y)\eta(Z)$$

Theorem 5.2. Let M be an n -dimensional M -Projective curvature tensor on ϵ -kenmotsu manifold is conservative, then M is an Einstein manifold if taking $\epsilon = 1$ and Ricci tensor of M has the form $S(Y, Z) = -\frac{1}{\epsilon}(n-1)g(Y, Z)$



6. Irrotational M -Projective curvature tensor on ϵ -kenmotsu manifold

Definition 6.1. The rotation (curl) of M-Projective curvature tensor on an ϵ -kenmotsu manifold M is defined as,

$$RotM = (\nabla_U M)(X, Y)Z + (\nabla_X M)(U, Y)Z + (\nabla_Y M)(X, U)Z - (\nabla_Z M)(X, Y)U. \quad (56)$$

In consequence of Binachi second identity for Riemannian connection ∇ , (56) becomes

$$RotM = -(\nabla_Z M)(X, Y)U. \quad (57)$$

If the M-Projective curvature tensor is irrotational, then $curlM = 0$ and so by (57), we get

$$(\nabla_Z M)(X, Y)U = 0, \quad (58)$$

which gives

$$\nabla_Z(M(X, Y)U) = M(\nabla_Z X, Y)U + M(X, \nabla_Z Y)U + M(X, Y)\nabla_Z U. \quad (59)$$

Putting $U = \xi$ in (59), we obtain

$$\nabla_Z(M(X, Y)\xi) = M(\nabla_Z X, Y)\xi + M(X, \nabla_Z Y)\xi + M(X, Y)\nabla_Z \xi. \quad (60)$$

Now, substituting $Z = \xi$ in (1) and using the relation (2, 3, 12, 14) and (18), we obtain

$$M(X, Y)\xi = \lambda[\eta(X)Y - \eta(Y)X], \quad (61)$$

where,

$$\lambda = \frac{1}{2} + \frac{\epsilon\lambda \cdot 1}{2(n-1)} \quad (62)$$

By virtue of (62) and (10) in (60), we have

$$M(X, Y)\xi = \frac{\lambda}{\epsilon}[g(Z, X)Y - g(Z, Y)X]. \quad (63)$$

In view of (1) and (63), we have

$$\frac{\lambda}{\epsilon}[g(Z, X)Y - g(Z, Y)X] = R(X, Y)Z - \frac{1}{2(n-1)}[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY] \quad (64)$$

Contracting above equation (64) over X and using (62), we get

$$S(Y, Z)\left(\frac{n}{n-1}\right) = g(Y, Z)\left[\frac{r}{2(n-1)} - \frac{\lambda}{\epsilon}(n-1)\right] \quad (65)$$

from (65), we have

$$r = -\frac{2\lambda}{\epsilon}(n-1)^2. \quad (66)$$

Thus, we state the following theorem:

Theorem 6.1. If the M-Projective curvature tensor on an ϵ -kenmotsu manifold M is irrotational, then the manifold is an Einstein manifold with constant scalar curvature $-\frac{2\lambda}{\epsilon}(n-1)^2$.

References

- [1]. Bejancu, "Real hypersurfaces of indefinite Kähler manifolds," *Pacific J. Math*, vol. 16, pp. 545–556, 1993.
- [2]. "Blaga: η -Ricci solitons on para-Kenmotsu manifolds," *Balkan J. Geom. Applicat*, vol. 20, pp. 1–13, 2015.
- [3]. U. C. De and A. Sarkar, "On ϵ -Kenmotsu manifold," *Hardonic J*, vol. 32, pp. 231–242, 2009.



- [4]. K. L. Duggal and R. Sharma, *Symmetries of space time and Riemannian manifolds*. Kluwer Acad. Publishers, 1999.
- [5]. L. P. Eisenhart, "Symmetric tensor of the second order whose first covariant derivatives are zero," *Tran. Amer. Math. Soc.* vol. 25, pp. 297-306, 1923.
- [6]. A. Haseeb, "De: η -Ricci solitions in ϵ -Kenmotsu manifolds," *J. Geom*, vol. 110, pp. 1-12, 2019.
- [7]. A. Haseeb, M. K. Khan, and M. D. Siddiqi, "Some more results on an ϵ -Kenmotsu manifold with a semi-symmetric metric connention," *Acta. Math. Univ. Comenianae*, LXXXV, pp. 9-20, 2016.
- [8]. A. Haseeb, "Some results on projective curvature tensor in an ϵ -Kenmotsu manifold," *Palestine J. Math*, vol. 6, pp. 196-203, 2017.
- [9]. K. Kenmotsu, "A class of almost contact Riemannian manifolds," *Tohoku Math. J. (2)*, vol. 24, no. 1, pp. 93-103, 1972.
- [10]. R. N. Sing, S. K. Pandey, G. Pandey, and K. Tiwari, "On a semi-symmetric metric connention in an ϵ -Kenmotsu manifold," *Commun. Korean Math. Soc*, vol. 29, pp. 331-343, 2014.
- [11]. V. Venkatesha, "Vishnuvardhana: ϵ -Kenmotsu manifolds admiting a semi-symmetric connection," *Italian J. Pure Appl. Math*, vol. 38, pp. 615-623, 2017.
- [12]. X. Xufeng and C. Xiaoli, "Two therems on ϵ -Sasakian manifolds," *Internat. J. Math. Math Sci*, vol. 21, pp. 249-254, 1998.
- [13]. C. S. Bagewadi and E. Kumar, *Notes on trans-Sasakian manifolds*, vol. 65. Tensor N.S, 2004.
- [14]. C. L. Bejan and M. Crasmareanu, "Second order parallel tensors and Ricci solitons in 3 - dimensional normal paracontact geometry," *Anal. Global Anal. Geom*, vol. 46, no. 2, pp. 117-127, 2014.
- [15]. D. E. Blair, "Contact manifolds in Riemannian geometry," 1976.
- [16]. S. K. Chaubey and R. H. Ojha, "On the M - projective curvature tensor of a Kenmotsu manifold," *Differ. Geom. Dyn. Syst*, vol. 12, pp. 52-60, 2010.
- [17]. U. C. De and A. Sarkar, "On ϵ -Kenmotsu manifolds," *Hardonic J*, vol. 32, pp. 231-242, 2009.
- [18]. A. Yildiz, U. C. De, and B. E. Acet, "On Kenmotsu manifolds satisfying certain curvature conditions," *SUT J. Math.*, vol. 45, no. 2, 2009.
- [19]. U. C. De, S. Mallick, "Space times admitting M - projective curvature tensor," *Bulg. J. Phys.*, vol. 39, pp. 331-338, 2012.
- [20]. A. Gray and L. M. Hervella, "The sixteen classes of almost Hermitian man-ifolds and their linear invariants," *Ann. Mat. Pura Appl*, vol. 123, no. 1, pp. 35-58, 1980.
- [21]. G. Ingalahalli and C. S. Bagewadi, "Ricci solitons in α -Sasakian manifolds," *ISRN Geom.*, vol. 2012, pp. 1-13, 2012.
- [22]. I. Mahai, R. Rosca, and P.-S. On Lorentzian, *Classical Anal-ysis, World Scien- tific Pable*. Singapore, 1992.
- [23]. J. C. Marrero, "The local structure of trans-Sasakian manifolds," *Ann. Mat. Pura Appl. (4)*, vol. 162, no. 1, pp. 77-86, 1992.
- [24]. K. Matsumoto, "On Lorentzian para contact manifolds," *Bull. Yamagata Univ. Natur. Sci*, vol. 12, pp. 151-156, 1989.
- [25]. R. S. Mishra, *Almost contact metric manifolds*, vol. 1. Lucknow: Tensor Society of India, 1991.
- [26]. R. H. Ojha, "M - projectively flat Sasakian manifolds," *Indian J. Pure Appl. Math*, vol. 17, pp. 481-484, 1986.
- [27]. G. P. Pokhariyal, R. S. and Mishra, "Curvature tensors and their relativistic signification II," *Yoko- hama Math. J.*, vol. 18, pp. 105-108, 1970.
- [28]. A. Prakash, M. Ahmad, and A. Srivastava, "M - projective curvature tensor on a Lorentzian para-Sasakian manifolds," *IOSR-JM*, vol. 6, no. 1, pp. 19-23, 2013.

